

CONFORMAL β -CHANGE OF FINSLER METRIC BY h-VECTOR

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Abstract: In this paper we investigate the necessary and sufficient conditions for conformal β -change of Finsler metric by h-vector to be a projective change. We also search out the condition under which this change converts a Douglas space into a Douglas space.

Key Words: Finsler metric, conformal β -change, h-vector, projective change, Douglas space.

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1. Introduction

Let $F^n = (M^n, L)$ be an n-dimensional Finsler space on the differentiable manifold M^n equipped with the fundamental function $L(x, y)$. Shibata [14], Prasad and Bindu Kumari [13] have studied the general case of β -change, that is, $L^*(x, y) = f(L, \beta)$, where f is a positively homogeneous function of degree one in L and β , and β given by $\beta(x, y) = b_i(x)y^i$ is a one-form on M^n . The β -change of special Finsler spaces has been studied by Shukla, Pandey and Khageshwar Mandal [19].

The conformal theory of Finsler space was initiated by Knebelman [8] in 1929 and has been investigated in detail by many authors (Hashiguchi [4], Izumi [5,6] and Kitayama [7]). The conformal change is defined as $L'(x, y) = e^{\sigma(x)}L(x, y)$, where $\sigma(x)$ is a function of position only and known as conformal factor. In 2008, Abed [1,2] introduced the change $L''(x, y) = e^{\sigma(x)}L(x, y) + \beta(x, y)$, which he called a β -conformal change. In 2009 and 2010, Nabil L. Youssef et al. [20,21] introduced the transformation $L'''(x, y) = f(e^{\sigma}L, \beta)$, which is β -change of conformally changed Finsler metric L . They have not only established the relationships between some important tensors of (M^n, L) and the corresponding tensors of (M^n, L''') , but have also studied several properties of this change.

The order of combination of the above two changes has been reversed in paper [18], where authors have applied β -change first and conformal change afterwards, i.e.,

$$L^{**}(x, y) = e^{\sigma(x)}f(L(x, y), \beta(x, y))$$

where $\sigma(x)$ is a function of x , $\beta(x, y) = b_i(x)y^i$ is a 1-form. They have called this change as conformal β -change of Finsler metric. In this paper they have investigated the condition under which a conformal β -change of Finsler metric leads a Douglas space into a Douglas space. They have also found the necessary and sufficient conditions for this change to be a projective change. Some properties of the conformal β -change have been studied in [17].

Now we assume that b_i in β is a function of x and y both and satisfies the condition $\frac{\partial b_i}{\partial y^j} = \rho h_{ij}$, where ρ is a scalar function of x, y and h_{ij} is the angular metric tensor of (M^n, L) . Thus we have supposed that b_i in β is an h -vector and with this supposition we deal with the change

$$\bar{L}(x, y) = e^{\sigma(x)} f(L(x, y), \beta(x, y)). \quad (1)$$

We call this change as conformal β -change of Finsler metric by h -vector. In this paper we investigate the necessary and sufficient condition for this change to be a projective change. We also search out the condition under which this change converts a Douglas space into a Douglas space.

The Finsler space equipped with the metric \bar{L} as given by (1) will be denoted by \bar{F}^n . Throughout the paper the quantities corresponding to \bar{F}^n will be denoted by putting bar on the top of them. Homogeneity of f gives

$$L f_1 + \beta f_2 = f \quad (2)$$

where subscripts 1 and 2 denote the partial derivatives with respect to L and β respectively. Differentiating above equations with respect to L and β respectively, we get

$$L f_{12} + \beta f_{22} = 0, L f_{11} + \beta f_{21} = 0. \quad (3)$$

Hence we have

$$f_{11}/\beta^2 = -f_{12}/L\beta = f_{22}/L^2, \quad (4)$$

which gives

$$f_{11} = \beta^2 w, f_{12} = -L\beta w, f_{22} = L^2 w, \quad (5)$$

where Weierstrass function w is positively homogeneous of degree -3 in L and β . Therefore

$$L w_1 + \beta w_2 + 3w = 0, \quad (6)$$

where w_1 and w_2 are positively homogeneous of degree -4 in L and β . Throughout the paper we frequently use the above equations without quoting them. Also we have assumed that f is not linear function of L and β so that $w \neq 0$.

The fundamental metric tensor g_{ij} , the normalized element of support l_i and angular metric tensor h_{ij} of F^n are given by

$$g_{ij} = \frac{1}{2} \frac{\partial^2 L^2}{\partial y^i \partial y^j}, \quad l_i = \frac{\partial L}{\partial y^i} \text{ and } h_{ij} = L \frac{\partial^2 L}{\partial y^i \partial y^j} = g_{ij} - l_i l_j .$$

We shall denote the partial derivative with respect to x^i and y^i by ∂_i and $\dot{\partial}_i$ respectively and write

$$L_i = \dot{\partial}_i L, \quad L_{ij} = \dot{\partial}_i \dot{\partial}_j L, \quad L_{ijk} = \dot{\partial}_i \dot{\partial}_j \dot{\partial}_k L .$$

Then

$$L_i = l_i, \quad L^{-1} h_{ij} = L_{ij} .$$

The geodesics of F^n are given by the system of differential equations

$$\frac{d^2 x^i}{ds^2} + 2G^i \left(x \frac{dx}{ds} \right) = 0,$$

where $G^i(x, y)$ are positively homogeneous of degree 2 in y^i and are given by

$$2G^i = g^{ij} (y^r \dot{\partial}_j \partial_r F - \partial_j F), \quad F = \frac{L^2}{2},$$

where g^{ij} are the inverse of g_{ij} .

The well known Berwald connection $B\Gamma = (G_{jk}^i, G_j^i, 0)$ of a Finsler space is constructed from the quantity G^i appearing in the equation of geodesic and is given by [10]:

$$G_j^i = \dot{\partial}_j G^i, \quad G_{jk}^i = \dot{\partial}_k G_j^i .$$

The Cartan's connection $C\Gamma = (F_{jk}^i, G_j^i, C_{jk}^i)$ is constructed from the metric function L by the following five axioms[10]:

$$(i) \ g_{ij|k} = 0, \quad (ii) \ g_{ij} |_k = 0, \quad (iii) \ F_{jk}^i = F_{kj}^i \quad (iv) \ F_{0k}^i = G_k^i, \quad (v) \ C_{jk}^i = C_{kj}^i,$$

where $|_k$ and $|_k$ denote h- and v-covariant derivatives with respect to $C\Gamma$. It is clear that the h-covariant derivative of L with respect to $B\Gamma$ and $C\Gamma$ is the same and vanishes identically. Furthermore, the h-covariant derivatives of L_i and L_{ij} with respect to $C\Gamma$ are also zero.

We shall use the following result obtained by Shukla, Pandey and Joshi [15]:

$$\dot{\partial}_k \rho = -\frac{\rho}{L} l_k, \quad n > 2. \tag{7}$$

We shall write

$$2r_{ij} = b_{ij} + b_{ji}, \quad 2s_{ij} = b_{ij} - b_{ji}. \tag{8}$$

2. Fundamental Quantities of (M^n, \bar{L})

To find the relation between fundamental quantities of (M^n, L) and (M^n, \bar{L}) , we use the following results:

$$\partial_i \beta = b_i, \partial_i L = l_i, \partial_j l_i = L^{-1} h_{ij} . \quad (9)$$

The successive differentiation of (1) with respect to y^i, y^j and y^k gives respectively:

$$\bar{L}_i = e^\sigma (f_1 L_i + f_2 b_i) : \quad (10a)$$

$$\bar{L}_{ij} = e^\sigma [\beta^2 w L_i L_j - \beta L w (L_i b_j + L_j b_i) + (f_1 + \rho L f_2) L_{ij} + L^2 w b_i b_j], \quad (10b)$$

where $\frac{\partial b^i}{\partial y^j} = \rho h_{ij} = \rho L L_{ij}$;

$$\begin{aligned} \bar{L}_{ijk} = e^\sigma & [(f_1 + \rho L f_2) L_{ijk} + (\beta^2 w - \rho \beta L^2 w) (L_i L_{jk} + L_j L_{ik} + L_k L_{ij}) \\ & + (-\beta L w + \rho L^3 w) (b_i L_{jk} + b_j L_{ik} + b_k L_{ij}) \\ & + (2\beta w + \beta^2 w_2) (L_i L_j b_k + L_i L_k b_j + L_j L_k b_i) \\ & - (L w + L \beta w_2) (L_i b_j b_k + L_j b_i b_k + L_k b_i b_j) \\ & + \beta^2 w_1 L_i L_j L_k - L^2 w_2 b_i b_j b_k] . \end{aligned} \quad (10c)$$

The differentiation of (10 a) with respect to x^j and (10 b) with respect to x^k gives respectively

$$\begin{aligned} \partial_j \bar{L}_i = e^\sigma & [(f_1 L_i + f_2 b_i) \partial_j \sigma + (\beta^2 w L_i - \beta L w b_i) \partial_j L \\ & + (-\beta L w L_i + L^2 w b_i) \partial_j \beta + f_1 \partial_j L_i + f_2 \partial_j b_i], \end{aligned} \quad (11a)$$

$$\begin{aligned} \partial_k \bar{L}_{ij} = e^\sigma & \{ (f_1 + \rho L f_2) L_{ij} + \beta^2 w L_i L_j - \beta L w (L_i b_j + L_j b_i) \\ & + L^2 w b_i b_j \} \partial_k \sigma + (f_1 + \rho L f_2) \partial_k L_{ij} + \{ (\beta^2 w + \rho f_2 - \rho \beta L^2 w) L_{ij} \\ & + \beta^2 w_1 L_i L_j - (\beta w + \beta L w_1) (L_i b_j + L_j b_i) + (2L w + L^2 w_1) b_i b_j \} \partial_k L \\ & + \{ (-\beta L w + \rho L^3 w) L_{ij} + (2\beta w + \beta^2 w_2) L_i L_j - (L w + \beta L w_2) (L_i b_j + L_j b_i) \\ & + L^2 w_2 b_i b_j \} \partial_k \beta + (\beta^2 w L_j - \beta L w b_j) \partial_k L_i + (\beta^2 w L_i - \beta L w b_i) \partial_k L_j \\ & + (L^2 w b_j - \beta L w L_j) \partial_k b_i + (L^2 w b_i - \beta L w L_i) \partial_k b_j + L f_2 L_{ij} \partial_k \rho] . \end{aligned} \quad (11b)$$

3. Difference Tensor of Conformal β -change of Finsler Metric by h-Vector

We may put

$$\bar{G}^i = G^i + D^i . \quad (12)$$

Then $\bar{G}_j^i = G_j^i + D_j^i$ and $\bar{G}_{jk}^i = G_{jk}^i + D_{jk}^i$, where $D_j^i = \partial_j D^i$ and $D_{jk}^i = \partial_k D_j^i$. The tensors D^i, D_j^i and D_{jk}^i are positively homogeneous in y^i of degree two, one and zero respectively.

To find difference tensor D^i we deal with equation $L_{ij|k} = 0$ [16], i.e.

$$\partial_k L_{ij} - L_{ijr} G_k^r - L_{rj} F_{ik}^r - L_{ir} F_{jk}^r = 0. \quad (13)$$

Since $\bar{L}_{ij\bar{k}} = 0$ in \bar{F}^n , after using (12), we have

$$\partial_k \bar{L}_{ij} - \bar{L}_{ijr}(G_k^r + D_k^r) - \bar{L}_{rj}(F_{ik}^r + {}^c D_{ik}^r) - \bar{L}_{ir}(F_{jk}^r + {}^c D_{jk}^r) = 0, \quad (14)$$

where $\bar{F}_{jk}^i - F_{jk}^i = {}^c D_{jk}^i$ [9].

Substituting in equation (14) the values of $\partial_k \bar{L}_{ij}$, \bar{L}_{ir} and \bar{L}_{ijr} from (11 b), (10 b) and (10 c) respectively, using (13) and then contracting the equation thus obtained with y^k we get

$$\{(f_1 + \rho L f_2)L_{ij} + \beta^2 w L_i L_j - \beta L w(L_i b_j + L_j L_i) + L^2 w b_i b_j\} \sigma_0 \quad (15)$$

$$\begin{aligned} & - 2\{(f_1 + \rho L f_2)L_{ijr} + (\beta^2 w - \rho \beta L^2 w)(L_i L_{jr} + L_j L_{ri} + L_r L_{ij}) \\ & + (-\beta L w + \rho L^3 w)(b_i L_{jr} + b_j L_{ir} + b_r L_{ij}) + (2\beta w + \beta^2 w_2)(L_i L_j b_r + L_i L_r b_j + L_j L_r b_i) \\ & - (L w + L \beta w_2)(L_i b_j b_r + L_j b_r b_i + L_r b_i b_j) + \beta^2 w_1 L_i L_j L_r \\ & + L^2 w_2 b_i b_j b_r\} D^r \\ & + \{(f_1 + \rho L f_2)L_{jr} + \beta^2 w L_r L_j - \beta L w(L_j b_r + L_r b_j) + L^2 w b_r b_j\} D_j^r \\ & + \{(f_1 + \rho L f_2)L_{ir} + \beta^2 w L_r L_i - \beta L w(L_i b_r + L_r b_i) + L^2 w b_r b_i\} D_j^r \\ & - (L^2 w b_j - \beta L w L_j)(r_{0i} + s_{0i}) - (L^2 w b_i - \beta L w L_i)(r_{0j} + s_{0j}) \\ & - \{(-\beta L w + \rho L^3 w)L_{ij} + (2\beta w + \beta^2 w_2)L_i L_j \\ & - (L w + \beta L w_2)(L_i b_j + L_j b_i) + L^2 w_2 b_i b_j\} r_{00} \\ & - L f_2 y^k L_{ij} \partial_k \rho - 2 \rho f_2 L_r L_{ij} G^r = 0, \end{aligned}$$

where we have used the fact that $D_{jk}^i y^k = {}^c D_{jk}^i y^k = D_j^i$ [9], and ‘0’ stands for contraction with respect to y^i , viz. $r_{0k} = r_{ik} y^i$, $r_{00} = r_{ij} y^i y^j$.

Next, we deal with $\bar{L}_{i\bar{j}} = 0$, i.e. $\partial_j \bar{L}_i - \bar{L}_{ir} \bar{G}_j^r - \bar{L}_r \bar{F}_{ij}^r = 0$ to get

$$\partial_j \bar{L}_i - \bar{L}_{ir}(G_j^r + D_j^r) - \bar{L}_r(F_{ij}^r + {}^c D_{ij}^r) = 0. \quad (16)$$

Putting the values of $\partial_j \bar{L}_i$, \bar{L}_{ir} and \bar{L}_r from (11 a), (10 b), (10 a) respectively in (16), using equation $\partial_j L_i - L_{ir} G_j^r - L_r F_{ij}^r = 0$ and then rearranging the terms, we get

$$f_2 b_{ij} = (f_1 L_i + f_2 b_i) \sigma_j + \{(f_1 + \rho L f_2)L_{ir} + \beta^2 w L_r L_i - \beta L w(L_i b_r + L_r b_i) + L^2 w b_r b_i\} D_j^r + (\beta L w L_i - L^2 w b_i)(r_{0j} + s_{0j}) + (f_1 L_r + f_2 b_r) D_{ij}^r - \rho L f_2 L_{ir} F_{ij}^r,$$

which, after using (8), gives

$$\begin{aligned}
2f_2r_{ij} = & -(f_1L_i + f_2b_i)\sigma_j - (f_1L_j + f_2b_j)\sigma_i \\
& + \{(f_1 + \rho Lf_2)L_{ir} + \beta^2wL_rL_i - \beta Lw(L_i b_r + L_r b_i) + L^2wb_r b_i\}D_j^r \\
& + \{(f_1 + \rho Lf_2)L_{jr} + \beta^2wL_rL_j - \beta Lw(L_j b_r + L_r b_j) + L^2wb_r b_j\}D_i^r \\
& + (\beta LwL_i - L^2wb_i)(r_{0j} + s_{0j}) \\
& + (\beta LwL_j - L^2wb_j)(r_{0i} + s_{0i}) + 2(f_1L_r + f_2b_r)D_{ij}^r, \tag{17}
\end{aligned}$$

and

$$\begin{aligned}
2f_2s_{ij} = & -(f_1L_i + f_2b_i)\sigma_j + (f_1L_j + f_2b_j)\sigma_i + \{(f_1 + \rho Lf_2)L_{ir} + \beta^2wL_rL_i - \\
& \beta Lw(L_i b_r + L_r b_i) + L^2wb_r b_i\}D_j^r - \{(f_1 + \rho Lf_2)L_{jr} + \beta^2wL_rL_j \\
& - \beta Lw(L_j b_r + L_r b_j) + L^2wb_r b_j\}D_i^r + (\beta LwL_i - L^2wb_i)(r_{0j} + s_{0j}) \\
& - (\beta LwL_j - L^2wb_j)(r_{0i} + s_{0i}). \tag{18}
\end{aligned}$$

Subtracting (17) from (15) and contracting the resulting equation with y^i , we obtain

$$\begin{aligned}
(f_1L_j + f_2b_j)\sigma_0 + (f_1L + f_2\beta)\sigma_j + \{-(f_1 + \rho Lf_2)L_{jr} \\
+ L\beta wL_j b_r + L\beta wL_r b_j - \beta^2wL_j L_r - L^2wb_j b_r\}D^r \\
- (L\beta wL_j - L^2wb_j)\frac{r_{00}}{2} - (f_1L_r + f_2b_r)D_j^r + f_2r_{0j} = 0. \tag{19}
\end{aligned}$$

Contracting (19) with y^j , we get

$$f\sigma_0 + f_2r_{00} = 2(f_1L_r + f_2b_r)D^r. \tag{20}$$

Adding (15) and (18) and contracting the resulting equation with y^j , we get

$$\begin{aligned}
\{(f_1 + \rho Lf_2)L_{ir} + L\beta w(L_i b_r + L_r b_i) + \beta^2wL_i L_r - L^2wb_i b_r\}D^r \\
= (L^2wb_i - L\beta wL_i)\frac{r_{00}}{2} + f_2s_{i0} + L\beta w(L_i\beta - Lb_i)\sigma_0 \\
+ \frac{1}{2}(f_1L_i + f_2b_i)\sigma_0 - \frac{1}{2}\sigma_i f. \tag{21}
\end{aligned}$$

In view of $LL_{ir} = g_{ir} - L_i L_r$, the equation (21) can be written as

$$\begin{aligned}
f_2s_{i0} - (L^2wb_i - L\beta wL_i)\frac{r_{00}}{2} + \frac{1}{2}(f_1L_i + f_2b_i)\sigma_0 - \frac{1}{2}\sigma_i f \\
= \left(\rho f_2 + \frac{f_1}{L}\right)g_{ir}D^r + \left\{\left(-\frac{f_1}{L} + \beta^2w - \rho f_2\right)L_i - L\beta wb_i\right\}L_r D^r \\
(L^2wb_i - L\beta wL_i)b_r D^r. \tag{22}
\end{aligned}$$

Contracting (22) with $b^i = g^{ij}b_j$, we get

$$\left\{-\frac{f_1\beta}{L^2} - L\beta w - \rho Lf_2\right\}L_r D^r + \left(\frac{f_1}{L} + L^2w\Delta + \rho f_2\right)b_r D^r$$

$$= \frac{L^2 w}{2} r_{00} + f_2 s_0 + \frac{1}{2} \left(\frac{f_1 \beta}{L} + f_2 b^2 \right) - \frac{1}{2} f \sigma_1, \tag{23}$$

where $\Delta = b^2 - \frac{\beta^2}{L^2}$ and $s_0 = s_{r_0} b^r$.

The equations (20) and (23) constitute the system of algebraic equations in $L_r D^r$ and $b_r D^r$ whose solution is given by

$$b_r D^r = \frac{(f L^3 w \Delta + f_1 f_2 \beta + \rho L \beta f_2^2) r_{00} + 2 f_1 f_2 L^2 s_0 + \{\beta(f_1 + \rho L f_2 + L^3 w \Delta) + L(f_1^2 \beta + L b^2 f_1 f_2)\} \sigma_0 - f_1 L^2 \sigma_1}{2 f (f_1 + \rho L f_2 + L^3 w \Delta)}, \tag{24}$$

and

$$L_r D^r = \frac{L(f_1 + \rho L f_2) f_2 r_{00} - f_2^2 L^2 s_0 + L\{f(f_1 + \rho L f_2 + L^3 w \Delta) + (L f_2^2 b^2 + \beta f_1 f_2)\} \sigma_0 - f f_2 L^2 \sigma_1}{2 f (f_1 + \rho L f_2 + L^3 w \Delta)}. \tag{25}$$

Contracting (22) by g^{ij} and putting the values of $b_r D^r$ and $L_r D^r$ from (24) and (25) respectively, we get

$$\begin{aligned} D^i = & \left[\frac{f_1 f_2 - f L \beta w + L f_2^2 \rho}{2 f (f_1 + \rho L f_2 + L^3 w \Delta)} r_{00} - \frac{L f_2 (f_1 f_2 - f L \beta w + L f_2^2 \rho)}{(f_1 + \rho L f_2 + L^3 w \Delta) (f_1 + \rho L f_2)} s_0 \right. \\ & + \frac{(f_1 f_2 - L \beta w f) \{L f \sigma_1 - (L b^2 f_2 + \beta f_1) \sigma_0\}}{2 f (f_1 + \rho L f_2 + L^3 w \Delta)} + \sigma_0 \Big] y^i + \left[\frac{L^3 w}{2 (f_1 + \rho L f_2 + L^3 w \Delta)} r_{00} \right. \\ & \left. - \frac{f_2 L^4 w}{(f_1 + \rho L f_2 + L^3 w \Delta) (f_1 + \rho L f_2)} s_0 + \frac{L f_2}{2 (f_1 + \rho L f_2)} \sigma_0 \right. \\ & \left. + \frac{L^3 w \{L f \sigma_1 - (L b^2 f_2 + \beta f_1) \sigma_0\}}{2 (f_1 + \rho L f_2 + L^3 w \Delta) (f_1 + \rho L f_2)} \right] b^i - \frac{L f}{(f_1 + \rho L f_2)} \sigma^i + \frac{L f_2}{f_1 + \rho L f_2} s_0^i. \end{aligned} \tag{26}$$

Proposition 3.1. The difference tensor $D^i = \bar{G}^i - G^i$ of the conformal β -change of Finsler metric by h-vector is given by (26).

4. Condition to be Projective Change

The Finsler space \bar{F}^n is said to be projective to Finsler space F^n if every geodesic of F^n is transformed to a geodesic of \bar{F}^n and vice-versa. It is well known that the change $L \rightarrow \bar{L}$ is projective iff $\bar{G}^i = G^i + P(x, y) y^i$, where $P(x, y)$ is a homogeneous scalar function of degree one in y^i , called projective factor [11]. Thus from (12) it follows that $L \rightarrow \bar{L}$ is projective iff $D^i = P y^i$. First we suppose that the conformal β -change of Finsler metric by h-vector is projective. Then from equation (26), we have

$$P y^i = \left[\frac{f_1 f_2 - f L \beta w + L f_2^2 \rho}{2 f (f_1 + \rho L f_2 + L^3 w \Delta)} r_{00} - \frac{L f_2 (f_1 f_2 - f L \beta w + L f_2^2 \rho)}{(f_1 + \rho L f_2 + L^3 w \Delta) (f_1 + \rho L f_2)} s_0 \right. \tag{27}$$

$$\begin{aligned}
& + \frac{(f_1 f_2 - L\beta w f)\{Lf\sigma_1 - (Lb^2 f_2 + \beta f_1)\sigma_0\}}{2f(f_1 + \rho Lf_2 + L^3 w \Delta)} + \sigma_0] y^i + \left[\frac{L^3 w}{2(f_1 + \rho Lf_2 + L^3 w \Delta)} r_{00} \right. \\
& \quad \left. - \frac{f_2 L^4 w}{(f_1 + \rho Lf_2 + L^3 w \Delta)(f_1 + \rho Lf_2)} s_0 + \frac{Lf_2}{2(f_1 + \rho Lf_2)} \sigma_0 \right. \\
& \left. + \frac{L^3 w\{Lf\sigma_1 - (Lb^2 f_2 + \beta f_1)\sigma_0\}}{2(f_1 + \rho Lf_2 + L^3 w \Delta)(f_1 + \rho Lf_2)} \right] b^i - \frac{Lf}{(f_1 + \rho Lf_2)} \sigma^i + \frac{Lf_2}{f_1 + \rho Lf_2} S_0^i.
\end{aligned}$$

Contracting (27) with $y_i (= g_{ij} y^j)$ and using the fact that $s_0^i y_i = 0$ and $y_i y^i = L^2$, we get

$$\begin{aligned}
P &= \frac{f_1 f_2 + Lf_2^2 \rho}{2f(f_1 + \rho Lf_2 + L^3 w \Delta)} r_{00} - \frac{Lf_2^2}{f(f_1 + \rho Lf_2 + L^3 w \Delta)} S_0 \\
& + \frac{Lff_2 \sigma_1 + \{f(f_1 + \rho Lf_2 + L^3 w \Delta) - f_2(Lb^2 f_2 + \beta f_1)\sigma_0\}}{2f(f_1 + \rho Lf_2 + L^3 w \Delta)}.
\end{aligned} \tag{28}$$

Putting the value of P from (28) in (27), we get

$$\begin{aligned}
& \beta w((f_1 + \rho Lf_2)r_{00} - 2Lf_2 s_0) y^i + Lf\sigma_1 - (Lb^2 f_2 + \beta f_1)\sigma_0 \\
& = L^2 w((f_1 + \rho Lf_2)r_{00} - 2Lf_2 s_0) b^i + 2f_2(f_1 + \rho Lf_2 + L^3 w \Delta) s_0^i \\
& - Lf(f_1 + \rho Lf_2 + L^3 w \Delta) \sigma^i.
\end{aligned} \tag{29}$$

Tranvecting (29) by b_i , we get

$$r_{00} = \frac{(Lb^2 f_2 + \beta f_1)\sigma_0 - Lf\sigma_1 - 2Lf_2 s_0}{(f_1 + \rho Lf_2)\Delta}. \tag{30}$$

Substituting the value of r_{00} from (30) in (28), we get

$$P = \frac{\{fL^3 w \Delta + f_2(Lb^2 f_2 + \beta f_1)\}\sigma_0 + Lff_2 \sigma_1 - 2f_2^2 s_0}{2f\Delta(f_1 + \rho Lf_2)}. \tag{31}$$

Eliminating P and r_{00} from (31), (30) and (27), we get

$$\begin{aligned}
s_0^i &= \left(b^i - \frac{\beta}{L^2} y^i \right) \frac{s_0}{\Delta f(f_1 + \rho Lf_2)} - \frac{(f_1 y^i + f_2 b^i)\sigma_0}{2Lf_2} + \frac{f}{2Lf_2} \sigma^i \\
& + \frac{Lf\sigma_1 - (Lb^2 f_2 + \beta f_1)\sigma_0 + fL^3 w \Delta s_0}{2f_2 L^4 w} b^i.
\end{aligned} \tag{32}$$

The equations (30) and (32) give the necessary conditions under which the conformal β -change of Finsler metric by h-vector becomes a projective change.

Conversely, if conditions (30) and (32) are satisfied, then putting these conditions in (26), we get

$$D^i = \left[\frac{\{fL^3 w \Delta + f_2(Lb^2 f_2 + \beta f_1)\}\sigma_0 + Lff_2 \sigma_1 - 2f_2^2 s_0}{2f\Delta(f_1 + \rho Lf_2)} \right] y^i,$$

i.e $D^i = Py^i$, where P is given by (31).

Thus \bar{F}^n is projective to F^n .

Theorem (4.1). The conformal β -change of Finsler metric by h-vector is projective if and only if (30) and (32) hold.

Corollary (4.1). When $\sigma = 0$, the change (1) becomes general β -change of Finsler metric by h-vector. Then the conditions for projective change as narrated in Theorem (4.1) reduce to the conditions as obtained in [19]:

$$r_{00} = \frac{-2Lf_2s_0}{(f_1+\rho Lf_2)\Delta}, s_0^i = \left(b^i - \frac{\beta}{L^2}y^i\right) \frac{s_0}{\Delta f(f_1+\rho Lf_2)}.$$

Corollary (4.2). When $\rho = 0$, the change (1) becomes simply conformal β -change. Then the conditions for projective change as stated in Theorem (4.1) reduce to the conditions as obtained in [18]:

$$r_{00} = \frac{(Lb^2f_2+\beta f_1)\sigma_0-Lf\sigma_1-2Lf_2s_0}{\Delta f_1},$$

$$s_0^i = \left(b^i - \frac{\beta}{L^2}y^i\right) \frac{s_0}{\Delta f f_1} - \frac{(f_1y^i + f_2b^i)\sigma_0}{2Lf_2} + \frac{f}{2Lf_2}\sigma^i$$

$$+ \frac{Lf\sigma_1-(Lb^2f_2+\beta f_1)\sigma_0+fL^3w\Delta\sigma_0}{2f_2L^4w} b^i.$$

5. The Conformal β -change of Finsler Metric by h-Vector of a Douglas Space

The notion of Douglas space has been introduced by the Basco and Matsumoto [3] as a generalization of Berwald space from the view-point of geodesic equation. It is remarkable that a Finsler space is a Douglas space or is of Douglas type iff the Douglas tensor vanishes identically.

The Finsler space F^n is called a Douglas space iff $G^iy^j - G^jy^i$ is homogeneous polynomial of degree three in y^i [12]. We shall write $hp(r)$ to denote a homogeneous polynomial in y^i of degree r. If we write $B^{ij} = D^iy^j - D^jy^i$, then from (26), we get

$$B^{ij} = \left[\frac{L^3w(f_1+\rho Lf_2)r_{00}-2f_2L^4ws_0}{2(f_1+\rho Lf_2)(f_1+L^3w\Delta+\rho Lf_2)} + \frac{L^3w\{Lf\sigma_1-(Lb^2f_2+\beta f_1)\sigma_0\}}{2f_1(f_1+L^3w\Delta+\rho Lf_2)} + \frac{Lf_2}{zf_1+\rho Lf_2}\sigma_0 \right]$$

$$(b^iy^j - b^jy^i) + \frac{Lf_2}{f_1+\rho Lf_2}(s_0^iy^j - s_0^jy^i). \tag{33}$$

If a Douglas space is transformed to a Douglas space by conformal β -change of Finsler metric by h-vector, then B^{ij} must be $hp(3)$ and vice-versa.

Theorem (5.1). The conformal β -change of Finsler metric by h-vector transforms a Douglas space into a Douglas space iff B^{ij} given by (33) is $hp(3)$.

Corollary (5.1). When $\sigma = 0$, then the condition under which a Douglas space is transformed to a Douglas space as obtained in Theorem (5.1) reduces to the condition as obtained in [19] for similar purpose.

Corollary (5.2). When $\rho = 0$, then the condition as obtained in Theorem (5.1) to lead a Douglas space to a Douglas space reduces to the condition as obtained in [18] for similar purpose.

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